EtherCAT Relay function

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This presentation should be considered as the personal views of the presenters and not as a formal position, explanation, or interpretation of IEEE and ETG.

More details can be found in the presentation from 2017:

https://www.ieee802.org/1/files/public/docs2017/liaison-ETG-streamAdaption-1117.pdf

The website of the EtherCAT Technology Group (ETG) provides further information about EtherCAT: <u>https://ethercat.org/en/tech_group.html</u>

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IEEE 802 challenge for high speed applications

- Efficiency: low byte count (8 bytes) needed vs. 84 octets minimum for Ethernet
- Delay: cable delay of fieldbusses vs. store and forward/bridging (passive media used for first solutions)
 + interfering traffic
- → Overall efficiency 3% (with 128 octets interfering traffic)
- This leads to the EtherCAT approach

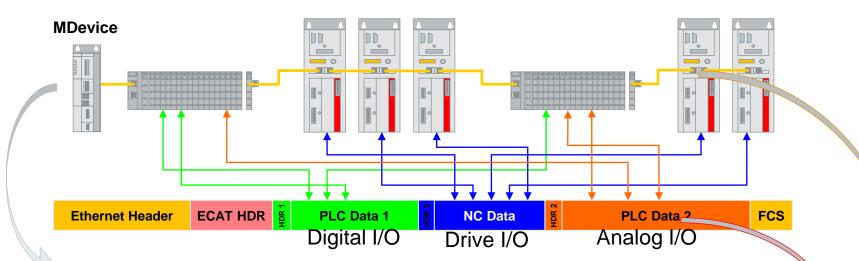




- Efficiency <u>Shared frame</u> instead of individual frame
 - ➔ performance improvement: overhead 50 Bytes instead of 750/1500 ... in a network of 10/20 I/O stations

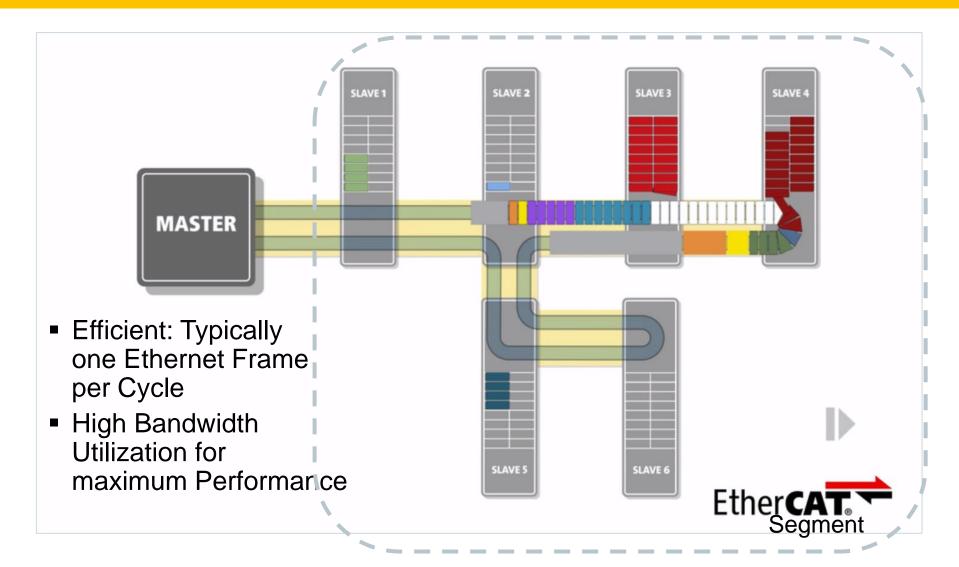
 Processing on the fly with topological relay function (automatic) Instead of address based forwarding
→ performance improvement: 0,6µs instead of >3µs (7µs/store&forward)

Functional Principle | Ethernet "on the fly"



- Ethernet-compatibility maintained
 - MDevice Implementation on standard Ethernet interface (MAC-Interface)
 - Standard PC or Embedded PC sufficient no dedicated plug-in card on-board Ethernet Port is fine
- Minimal overhead (= shared frame)
 - Optimized frame structure for I/O modules connected
 - L2 Communication in hardware within segment: **predictable** performance
 - No bridging, just relaying to next station in the loop

Functional Principle: Ethernet "on the fly"



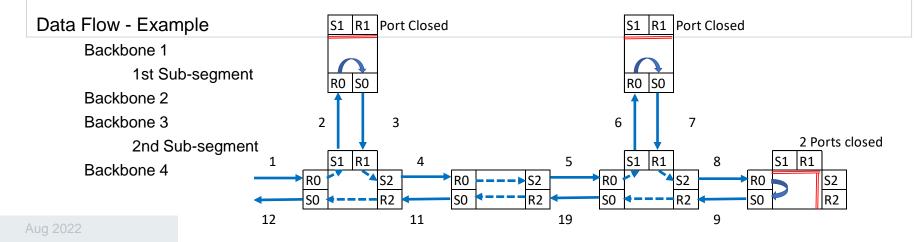
*Master/Slave shall be replaced by MDevice/SubDevice

Animation available as EtherCAT Functional Principle (2D) on https://www.youtube.com/watch?v=z2OagcHG-UU

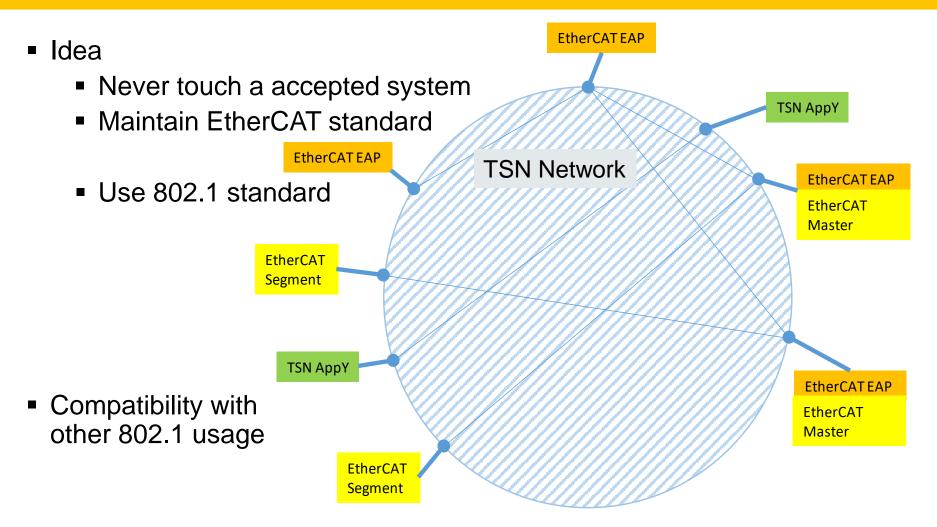
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Preconditions for the segment forwarding

- Same Data Rate within the segment (typical 100 Mb/s 1000 Mb/s possible)
- The MDevice will send out frames and receive frames
- Each SubDevice in the Segment just relays frames to the next port
- The forwarding acts as a <u>unidirectional relay</u> from port to port
 - Receive Port 0 connected to a virtual Port to allow a DLL entity to put information in the frame and get information "on the fly"
 - The forwarding takes place on any open port
 - The forwarding already starts with the Preamble
- If there is only one port open the relay function will send it back at the same port
- Each device that is connected will receive the frame
- The flow of data in a segment forms a logical ring of all devices connected
- → The ports of a node are ordered as a ring with Port0 as first entry
- ➔ If the main structure is a line, the exits of the line shall be in between Port0 and Port(last) for easier handling and diagnostic (no technical reason)

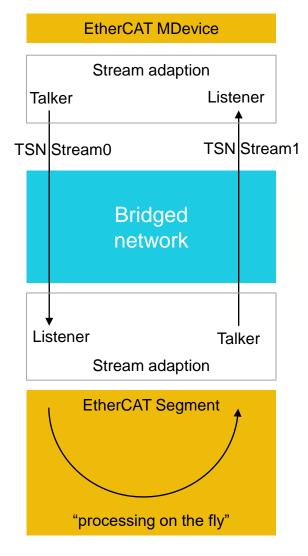


Use of Open mode -> TSN



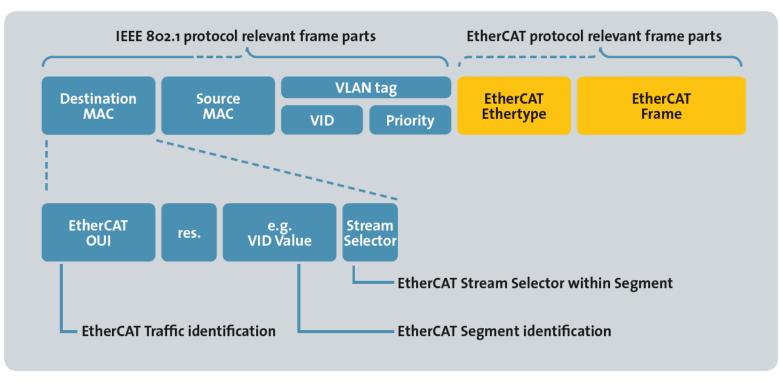
Specifies adaptation

Stream Adaptation: Details



- Always a pair of streams is set up
- Minimum one <u>pair</u>, but more might be set up, e.g.
 - One for cyclic
 - One for acyclic (strict priority)
 - for additional transfers
- Traffic class for pair of stream always the same
- Maintain Traffic Class (VLAN Prio)
- Maintain length (EtherCAT Rx/TX frame length identical)
- Unique Stream Identification required(!)

Protocols use different fields



Open Mode

- EtherCAT segment corresponds to an Identifier ("VID")
- MAC addresses for stream identification (StreamDA, StreamSA) constructed of
 - OUI, (V)ID, Stream selector
- Multicast DAs are possible as stream MAC for TSN Networks Null Stream Identification combined with Source MAC and VLAN Stream Identification according to Table 6-1 of 802.1CB
- Unicast DAs are possible for streams to the segment Address change for backward direction to avoid multicast scans in the MDevice and enables address learning in network